

# STRUCTURAL AND SURFACE ANALYSIS

## ATOMIC FORCE MICROSCOPY

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# ATOMIC FORCE MICROSCOPY

- Aim:

*acquisition of three-dimensional, spatially localized images revealing structure and properties of investigated material*

- ❖ belongs to the group of Scanning Probe Microscopy (SPM) techniques
- ❖ beginning dates back to the 80s of the XXth century
- ❖ 1982 - Gerd Binnig, Heinrich Rohrer – invention of Scanning Tunnelling Microscopy (STM) – Nobel Prize in physics (1986)
- ❖ 1986 – Gerd Binnig, Calvin Quate, Christopher Gerber – Atomic Force Microscopy (AFM)
- ❖ obtained image is not optical, but it results from interaction between the probe (tip) and the investigated surface
- ❖ the technique can be applied to conductive as well as non-conductive materials
- ❖ nanotechnological tool, which allows obtaining the images with atomic resolution (in advantageous conditions)

# TYPES OF ATOMIC INTERACTIONS

- short-range interactions
  - van der Waals forces responsible for formation of solids or the phenomenon of wetting the surface of solids by liquids
  - within the distance of few nanometres these forces are capable of moving macroscopical objects, for instance probe of the AFM
  - the main components of van der Waals forces:
    - polarization connected with permanent dipoles,
    - induced dipoles

# TYPES OF ATOMIC INTERACTIONS

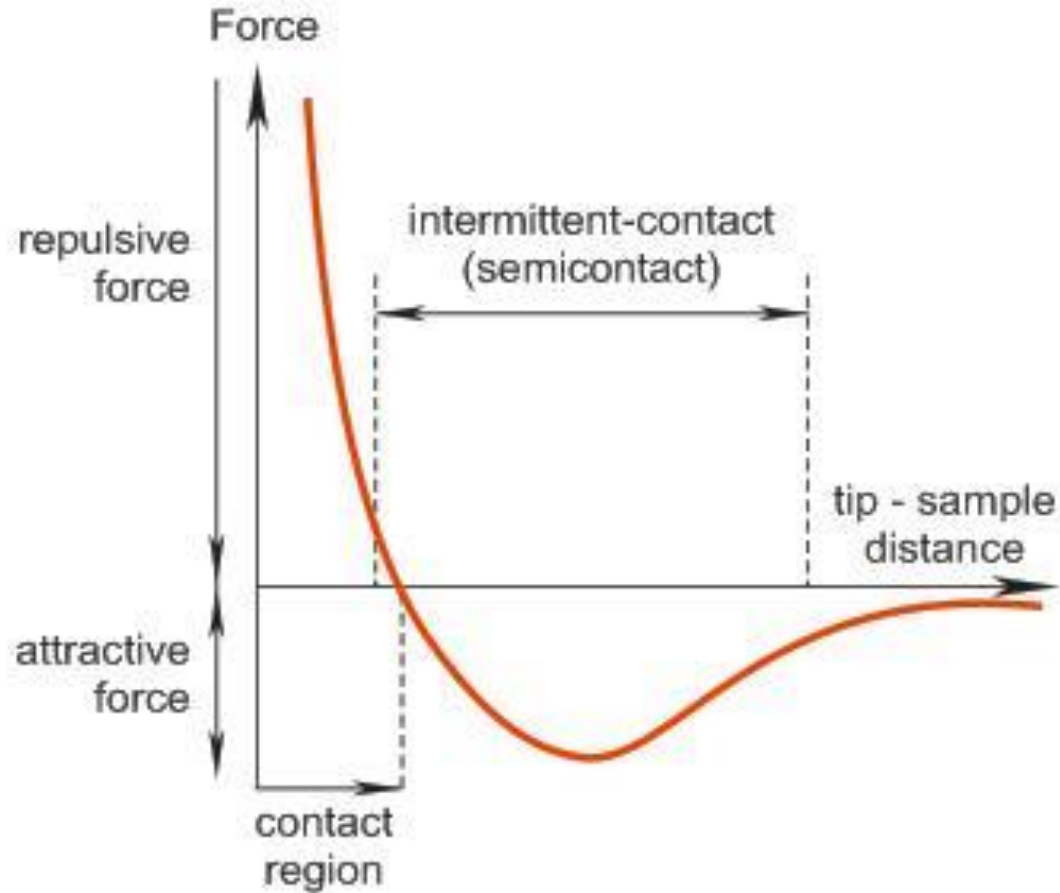
Distance [nm]	1	10	100
Force [N]	$10^{-9}$	$10^{-11}$	$10^{-13}$

*detection threshold in the AFM technique:  $10^{-18}$  N, easily measurable:  $10^{-15}$  N*

*Tab. 1 Van der Waals forces between two bodies versus distance between them*

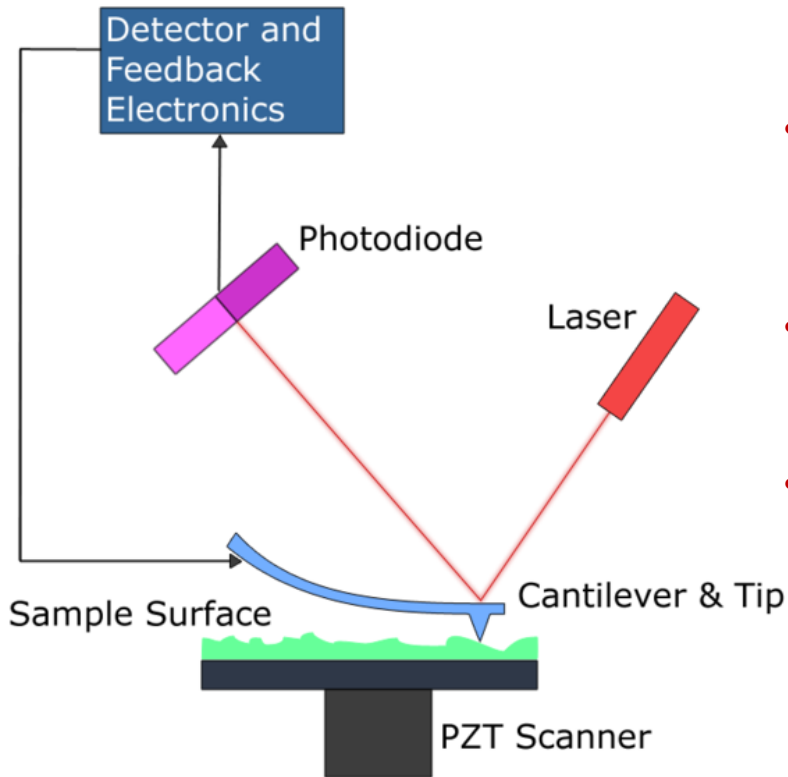
- long-range interactions
  - attractive or repulsive electrostatic forces, magnetic forces,
  - detection of particular types of forces requires application of suitable tip (for example coated with platinum or cobalt alloys)

# TYPES OF ATOMIC INTERACTIONS



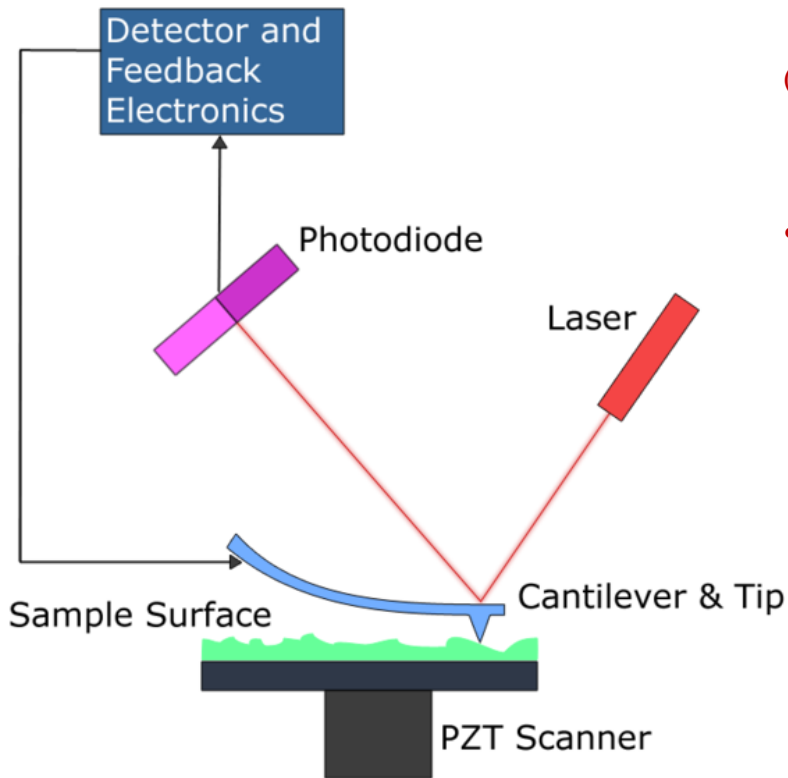
*Interaction between two bodies versus distance between them*

# ATOMIC FORCE MICROSCOPE

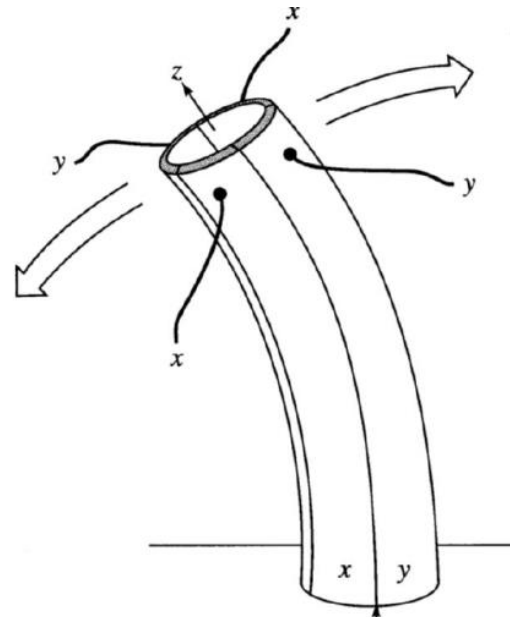


- is comprised of a cantilever made of silicon or silicon nitride terminated with a tip, which is used to scan the surface of investigated material
- motion of the tip versus the surface results in varying magnitude of atomic forces acting on the tip, which causes bending of the cantilever
- typically, bending of the cantilever is measured with a laser beam reflected from the top of it and directed to a photodiode detector

# ATOMIC FORCE MICROSCOPE



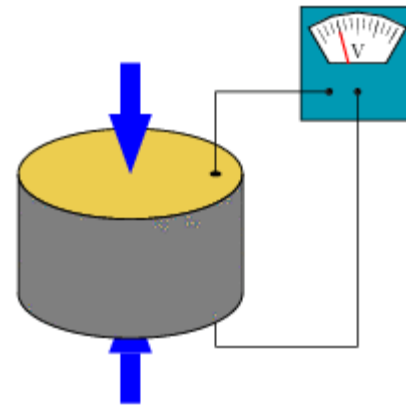
- SCANNING MODES:
  - (1) scanning by sample – sample moves in x and y directions with respect to the immobile tip
  - (2) scanning by tip – tip moves in x and y directions with respect to the immobile sample
- precise scanning motion is provided by piezoelectric element



- typical scanning ranges:  $1\ \mu\text{m}$ ,  $10\ \mu\text{m}$ ,  $100\ \mu\text{m}$  along horizontal plane

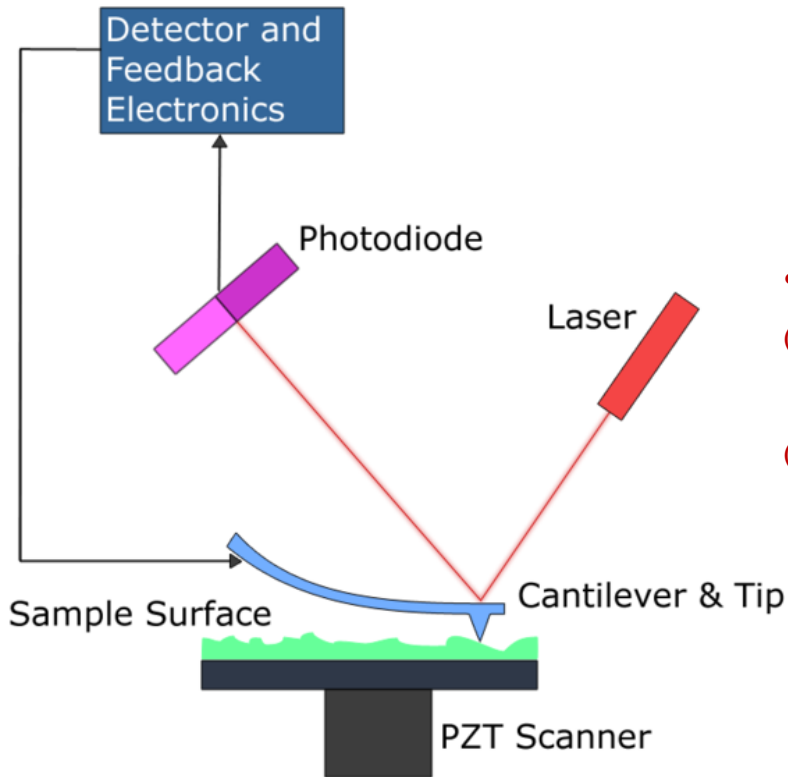
# PIEZOELECTRICITY

- ❖ generation of voltage by the elements subjected to mechanical compression or tension
- ❖ dimensional changes of these elements due to applied voltage
- ❖ magnitude of generated voltage is proportional to the magnitude of force applied
- ❖ reversible phenomenon





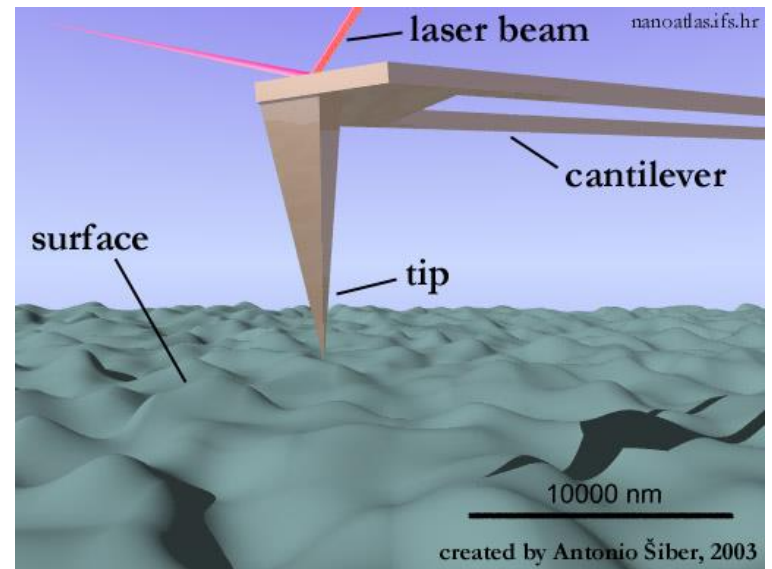
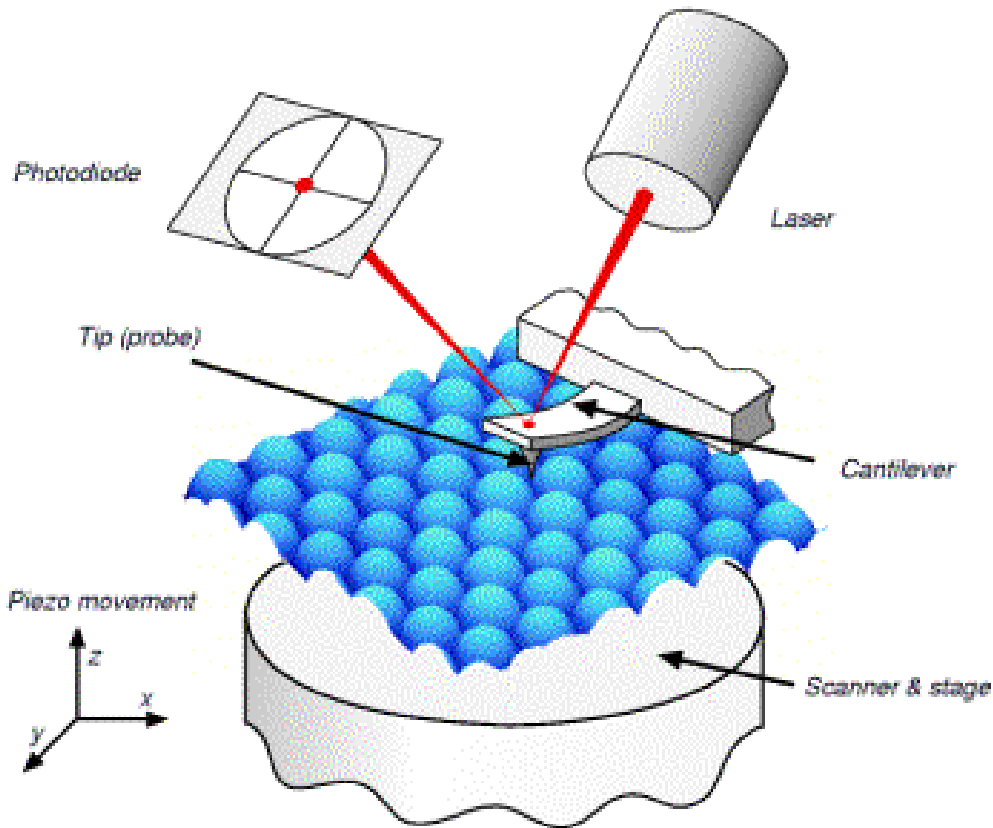
# ATOMIC FORCE MICROSCOPE



- MEASUREMENT MODE:

- (1) contact – the tip remains in contact with the investigated surface, application: hard materials (for example metals, ceramics)
- (2) non-contact – the tip moves within a small distance from the surface, application: soft materials (for example polymers, biological films)

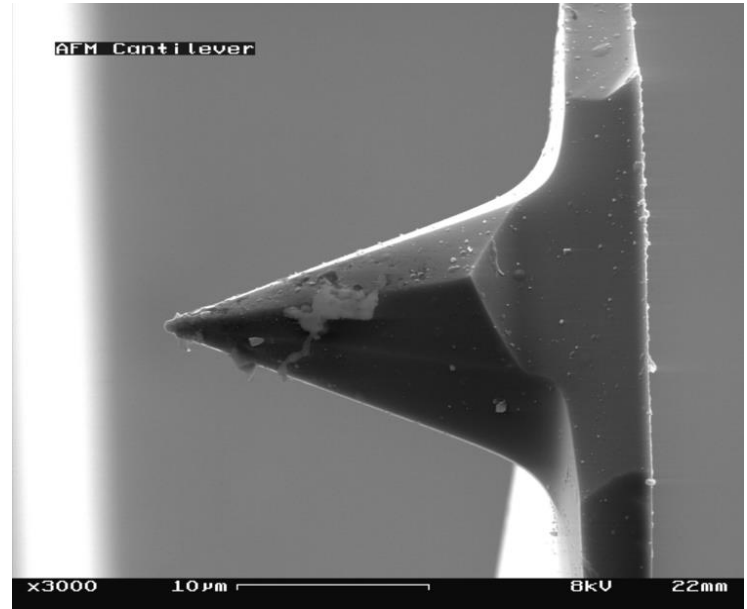
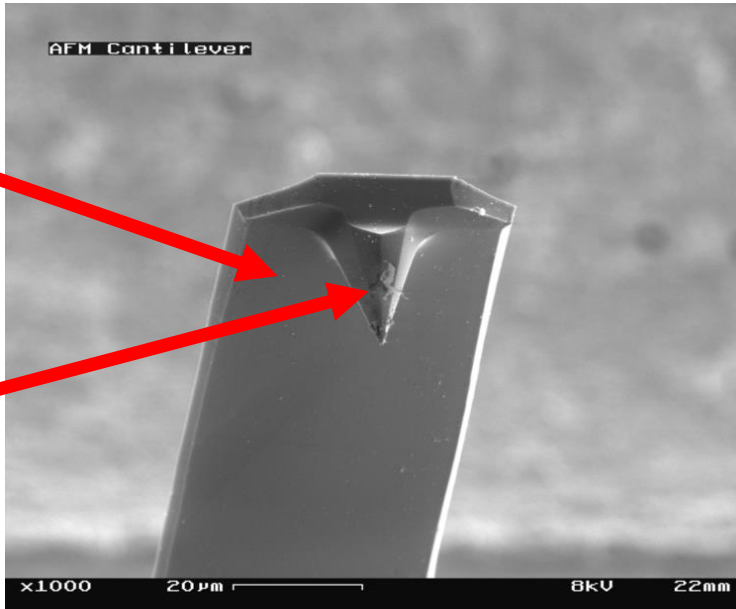
# ATOMIC FORCE MICROSCOPE



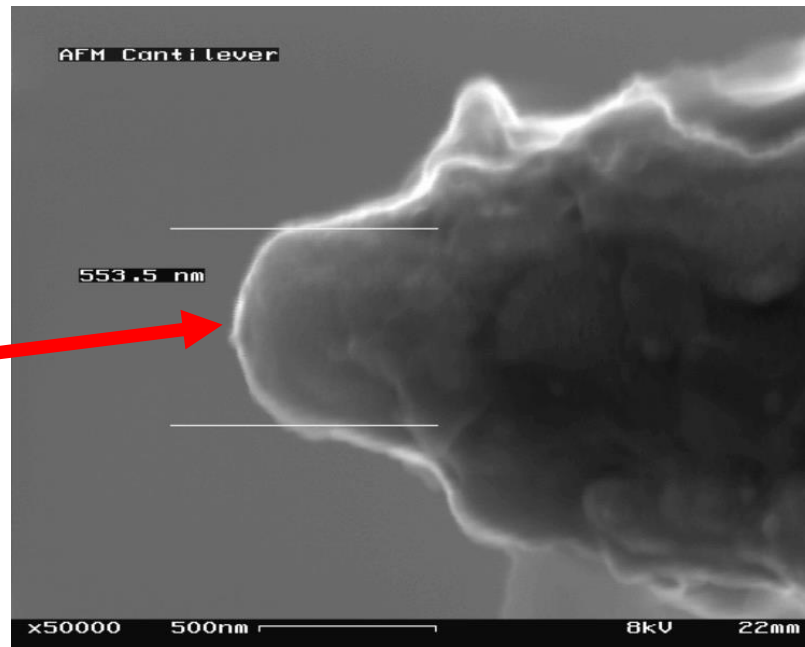
*Surface imaging by the AFM technique via optical detection of cantilever bending*

Cantilever  
100-500 $\mu$ m

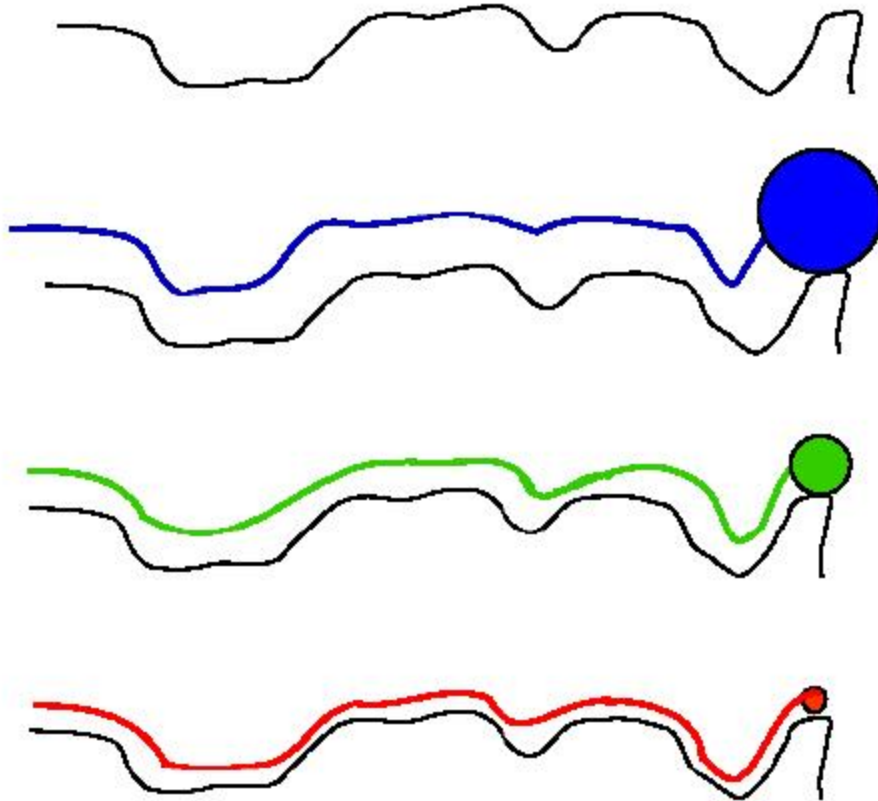
Tip



Tip curvature radius  
(typically 10-20nm)

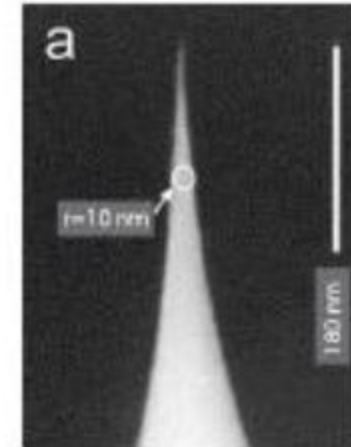


# ATOMIC FORCE MICROSCOPE

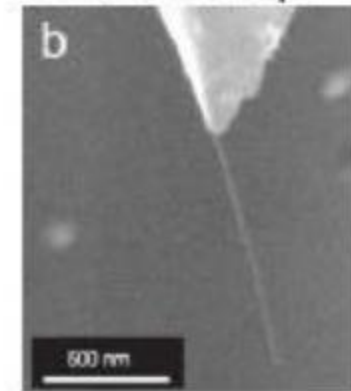


- suitable ratio of tip height to tip width (so-called aspect ratio) provides accuracy of surface imaging
- it is especially important in case of rough surfaces with significant differences in height profile

ultrasharp tip



nanotube tip



# ATOMIC FORCE MICROSCOPE

All systems of atomic force microscopy consist of five basic elements:

- tip,
- scanner,
- cantilever bending detection system,
- controller,
- anti-vibration system.

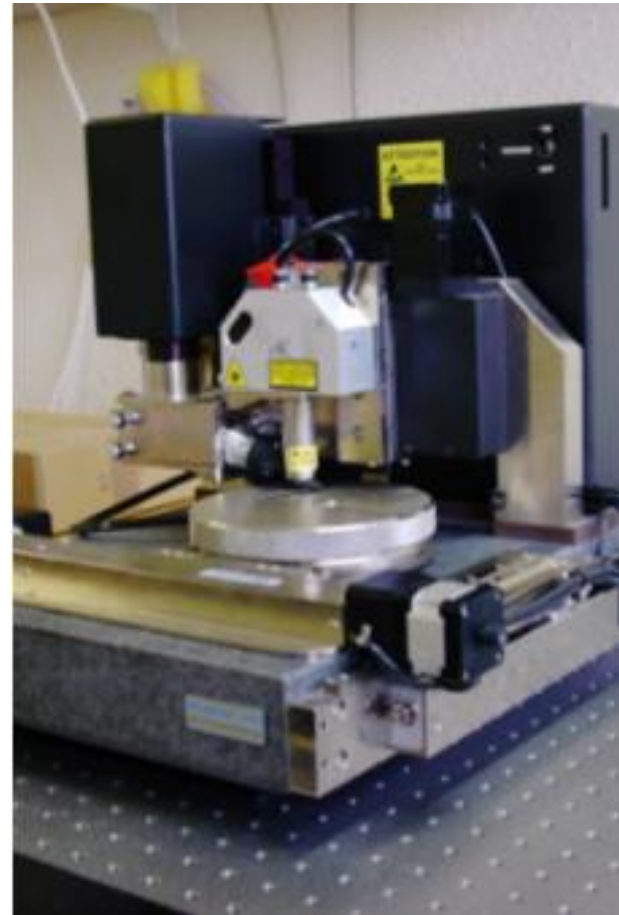
# ATOMIC FORCE MICROSCOPE

## Isolation from vibration

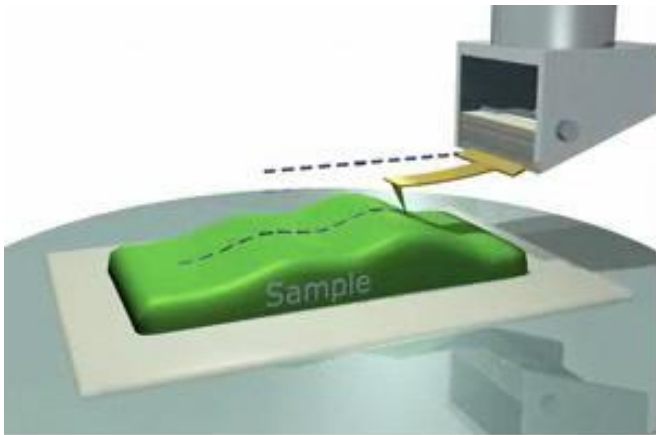
Suspended table



Anti-vibration table



# MEASUREMENT MODES



Vertical tip position



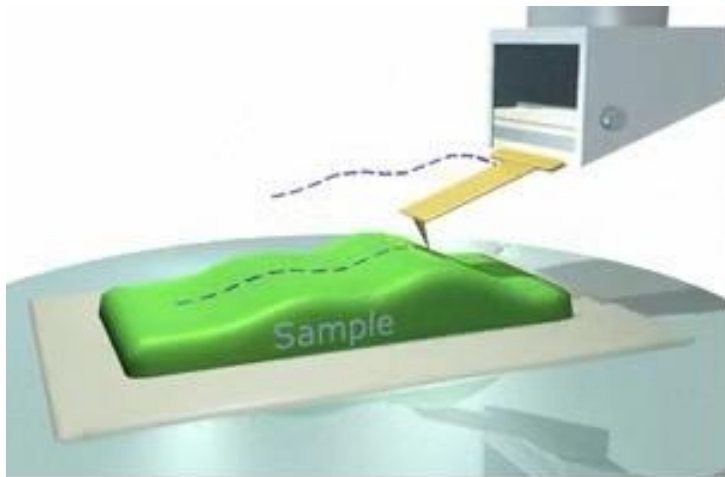
Cantilever deflection



- **CONSTANT HEIGHT MODE:**

- (1) a scanner is kept at constant height above the surface during measurement
- (2) cantilever deflection during tip motion is used to reconstruct surface topography profile of the sample
- (3) high scan rates possible
- (4) problems with measurement on the surfaces with significant roughness

# MEASUREMENT MODES



Vertical tip position



Cantilever deflection

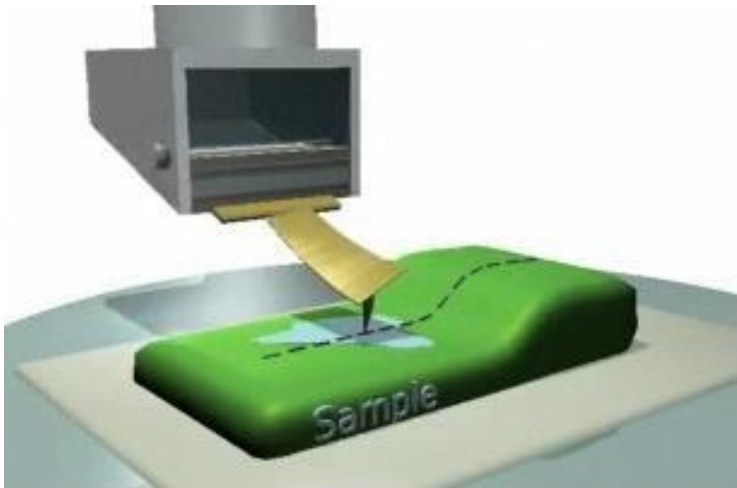


- **CONSTANT FORCE MODE:**

- (1) constant cantilever deflection is maintained during measurement
- (2) constant cantilever deflection is maintained by vertical motions of the scanner
- (3) vertical positioning of the scanner is used to reconstruct surface topography profile of the sample
- (4) **limited scan rate**



# MEASUREMENT MODES



Angle of cantilever twisting →



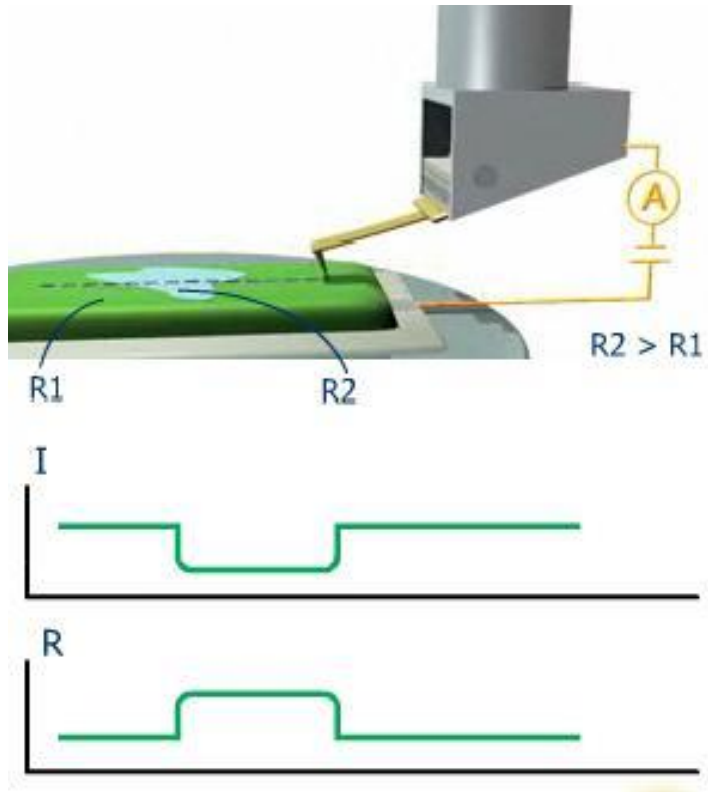
Angle of cantilever twisting ←



- **LATERAL FORCE IMAGING:**

- (1) due to friction forces the cantilever with tip undergoes twisting during measurement
- (2) possibility of detection of the domains differing in coefficient of friction (not necessarily differing in topography)
- (3) obtaining images with better resolved edges, corners and abrupt changes of profile
- (4) application: polymers, semiconductors, data storage devices, deposits, identification of surface contaminants

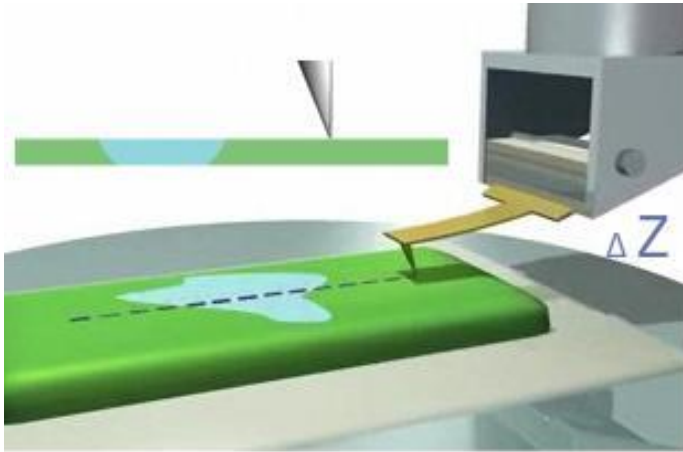
# MEASUREMENT MODES



- **SPREADING RESISTANCE IMAGING**

- (1) application of bias voltage between the tip and the investigated sample; then measurement of flowing direct current
- (2) possibility of detection of the domains differing in conductivity
- (3) the measurements must be carried out in contact mode
- (4) the tip must be coated with platinum layer or doped with diamond to provide conductivity
- (5) reliable results require appropriate contact force between the tip and the surface
- (6) application: quality control of electronic printed boards

# MEASUREMENT MODES



- **FORCE MODULATION MODE:**

- (1) the cantilever with tip oscillates along vertical axis
- (2) during scanning the tip penetrates the surface to a depth depending on material's hardness
- (3) oscillation amplitude and cantilever deflection change
- (4) possibility of determination of local rigidity, elasticity and microhardness of particular domains on investigated surface
- (5) application: polymers, semiconductors, biological materials, composite materials

Tip position



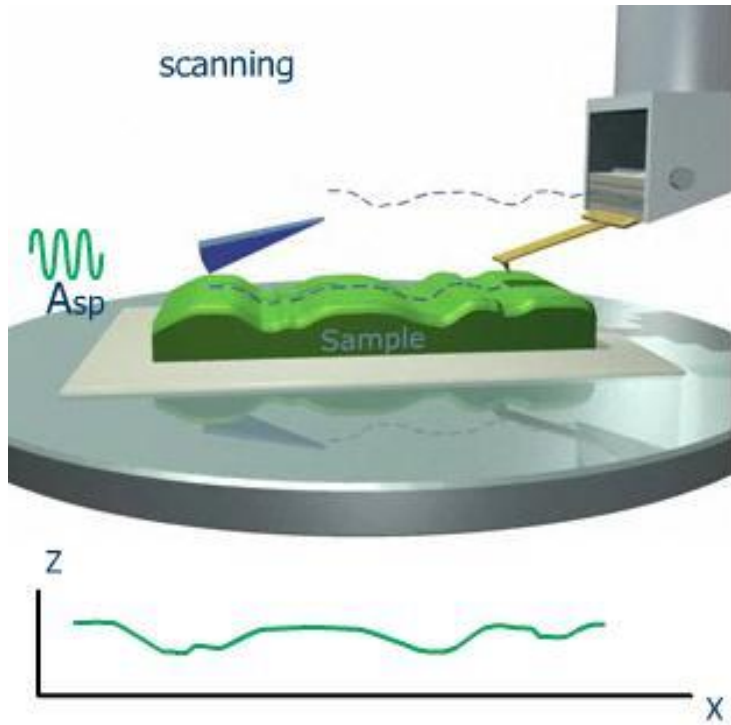
Cantilever deflection



Stiffness



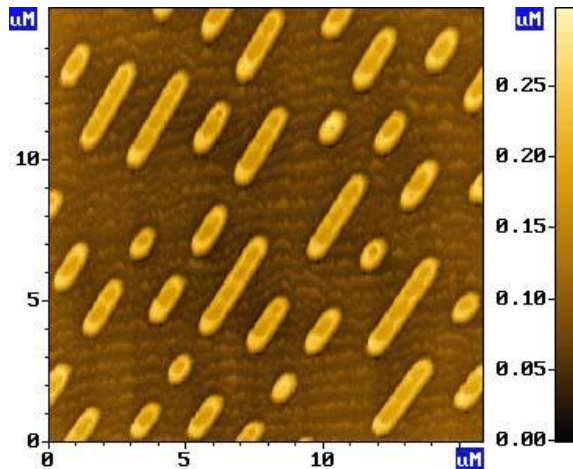
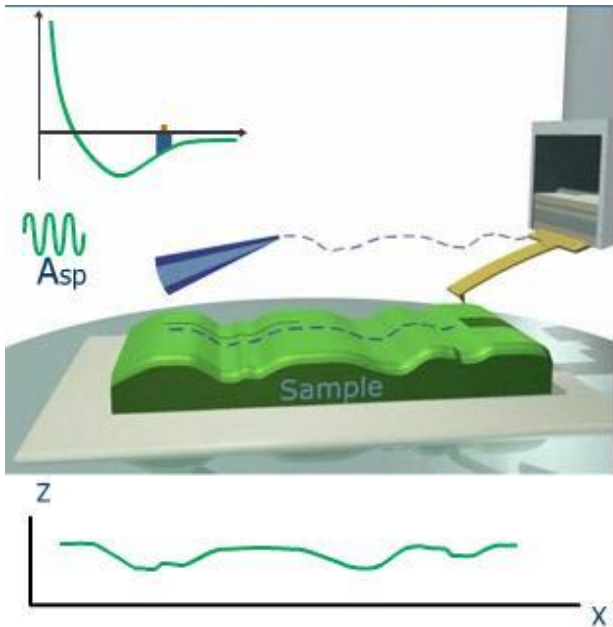
# MEASUREMENT MODES



- **NON-CONTACT MODE:**

- (1) the cantilever with tip oscillates **above** investigated surface
- (2) the cantilever oscillates with resonant frequency (3-500Hz)
- (3) when passing above particular regions the frequency of oscillation changes due to atomic forces impact
- (4) change in the oscillation frequency is used to reconstruct topographic image
- (5) application: biological materials, soft samples, which can be damaged while measured in contact mode

# MEASUREMENT MODES



- **NON-CONTACT MODE – in long-range interaction distance:**
  - (1) the cantilever with tip oscillates **above** investigated surface in the **distance**, which is **far enough** to expose the tip to long-range forces
  - (2) the cantilever oscillates with resonant frequency
  - (3) when passing above particular regions the frequency of oscillation changes due to long-range atomic forces impact
  - (4) change in the oscillation frequency is used to reconstruct topographic image
  - (5) in practice the measurement involves two passes: **(1)** topographic image is acquired when passing in direct vicinity of the surface, **(2)** profile connected with long-range interaction is acquired when passing at a certain distance from the surface
  - (6) application: materials with magnetic domains, for example data storage devices

# MEASUREMENT MODES



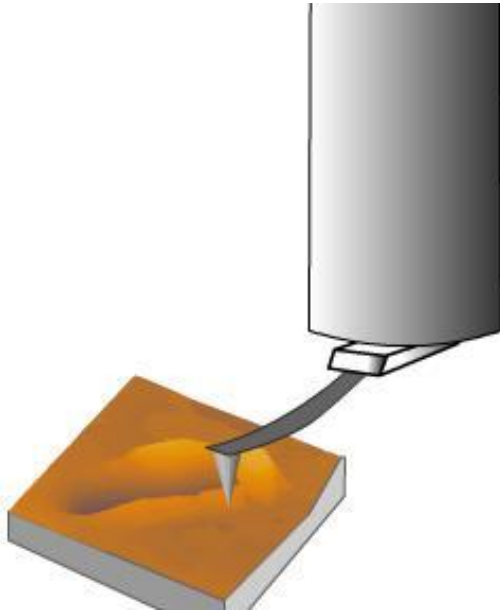
- **LITHOGRAPHY:**

- (1) surface modification via interaction with the tip
- (2) allows creation of a desired pattern on the surface
- (3) requires application of hard tips depending on the material to be grooved

**TYPES OF LITHOGRAPHY:**

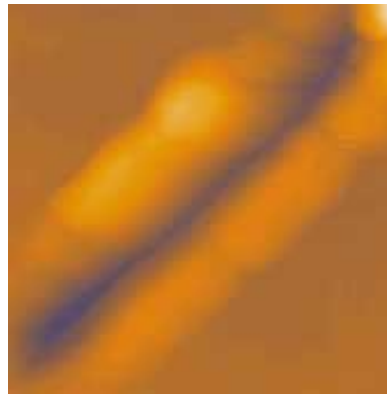
- stylus
- pinhole
- oxidation

# MEASUREMENT MODES



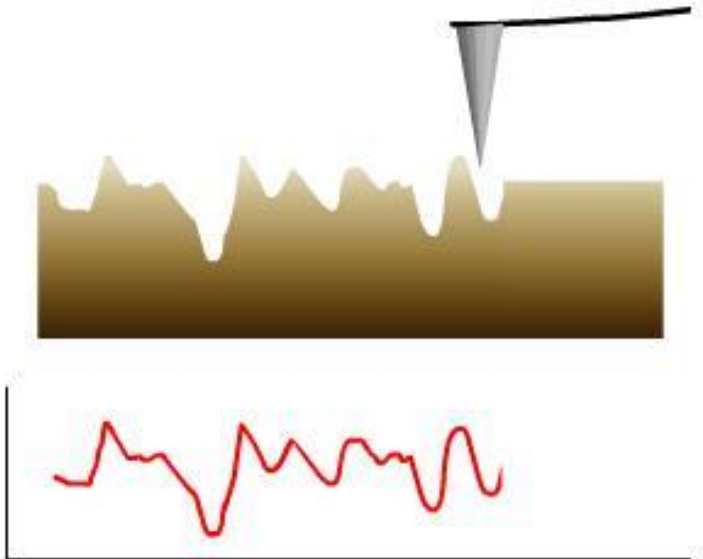
- **STYLUS LITHOGRAPHY:**

- (1) scratching the material with hard tip
- (2) usually performed on polymeric materials
- (3) requires sufficient contact force to make the tip penetrate the material



**1.6 x 1.6  $\mu\text{m}$**

# MEASUREMENT MODES



- **PINHOLE LITHOGRAPHY:**

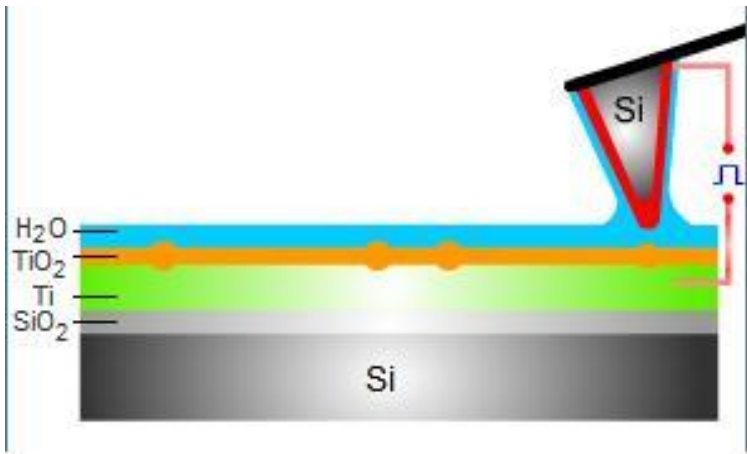
- (1) indentation of the material with hard tip
- (2) typically performed on polymeric materials
- (3) calls for sufficient amplitude of tip oscillation, which ensures tip penetration down the material



**2.5 x 2.5  $\mu\text{m}$**

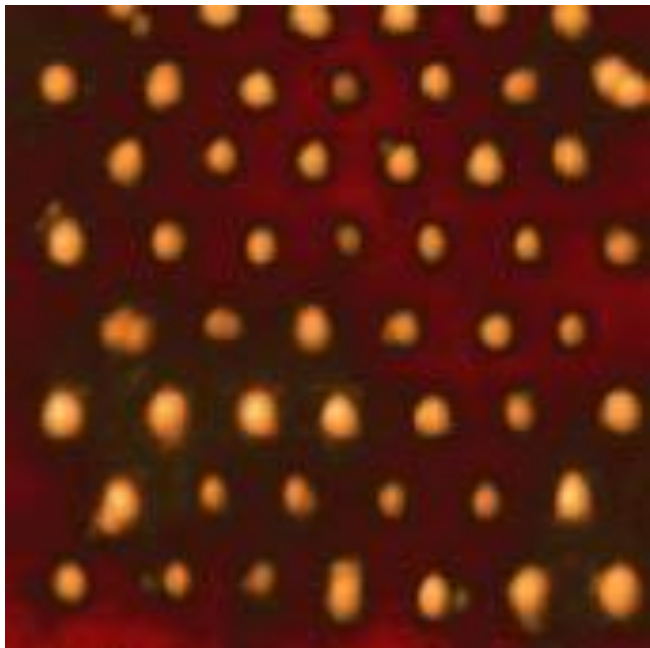


# MEASUREMENT MODES



- **OXIDATION LITHOGRAPHY:**

- (1) enforcing electrochemical reaction on the surface of the material, in the place of tip positioning
- (2) the reaction is enforced by application of proper bias voltage between the tip and the scanned material
- (3) presence of electrolyte is necessary
- (4) applicable for the surfaces where electrochemical reaction can occur, for instance metals and alloys

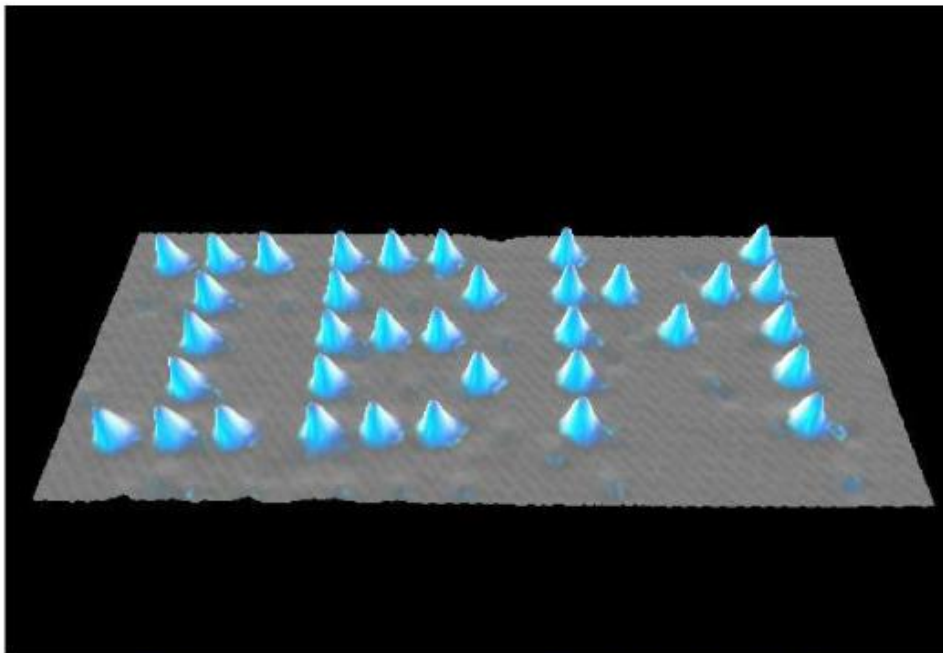
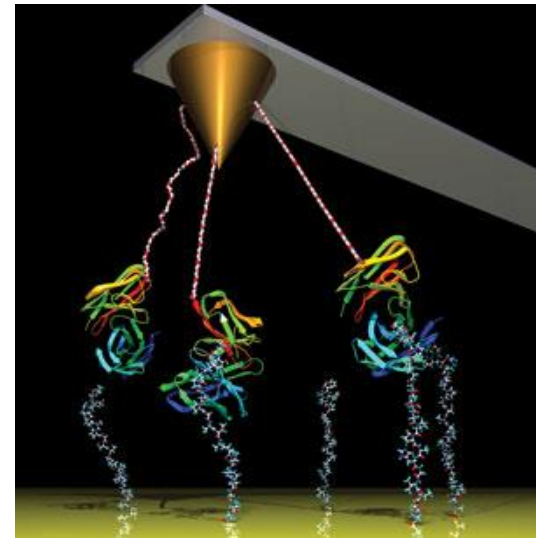


200 x 200 nm

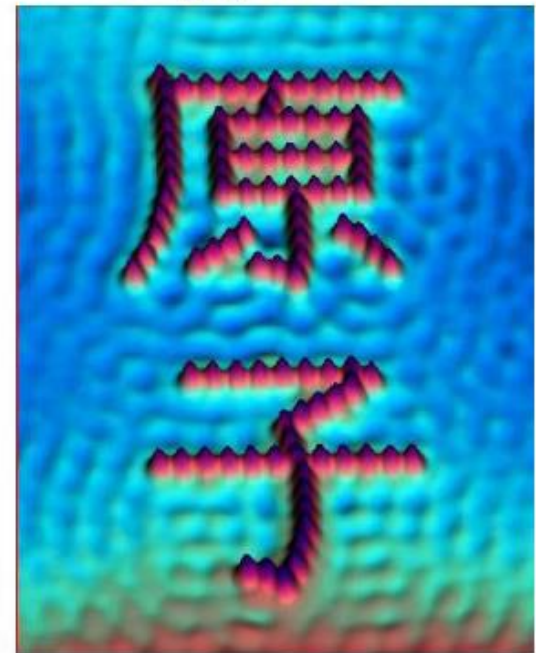
*Titanium oxide dots on the surface of metallic titanium*

# NANOGRAPHICS

- transfer („curling”) and positioning of individual atoms using the AFM tip

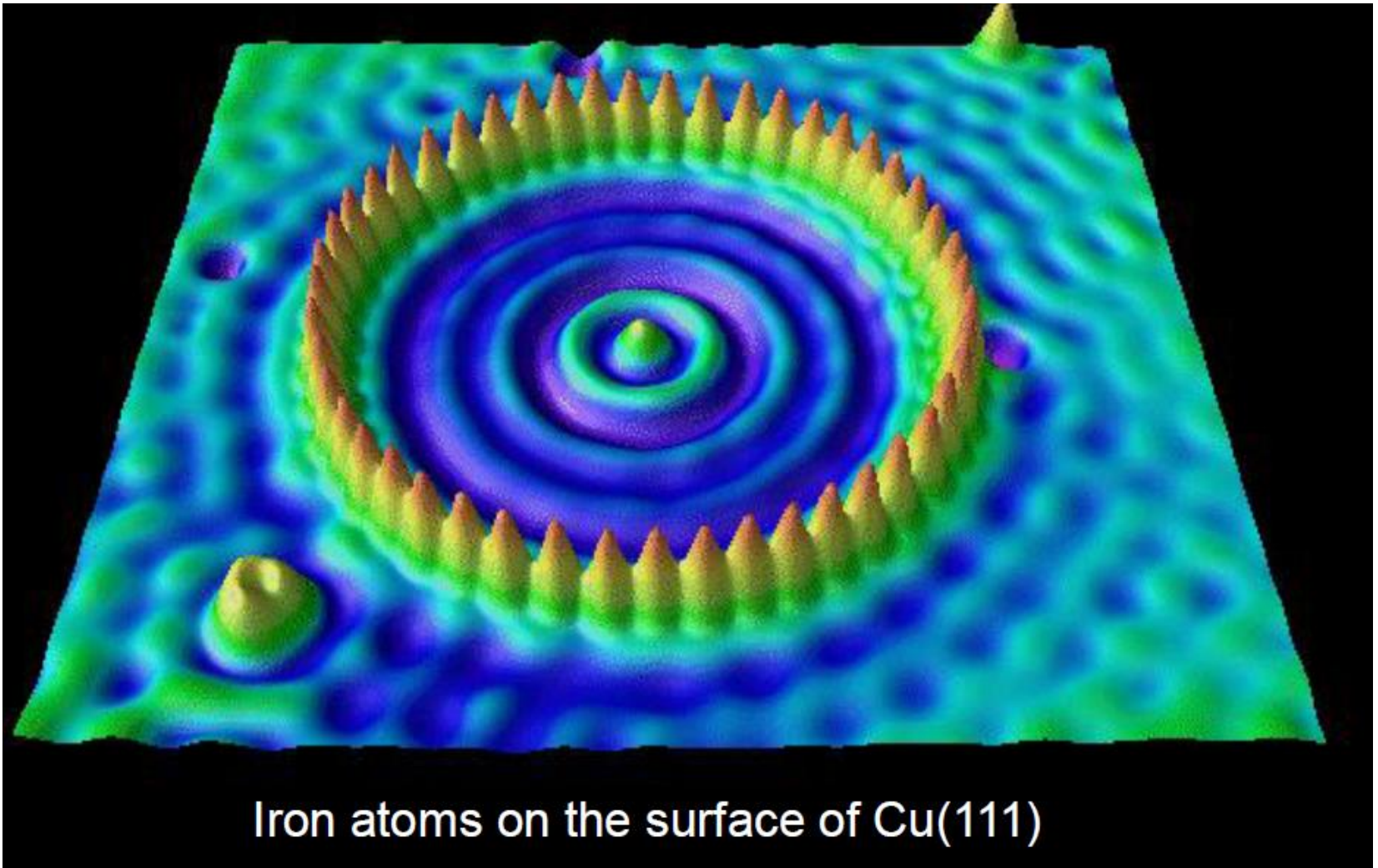


**Xenon atoms on Nickel (110)**



**Fe atoms on Cu(111)**

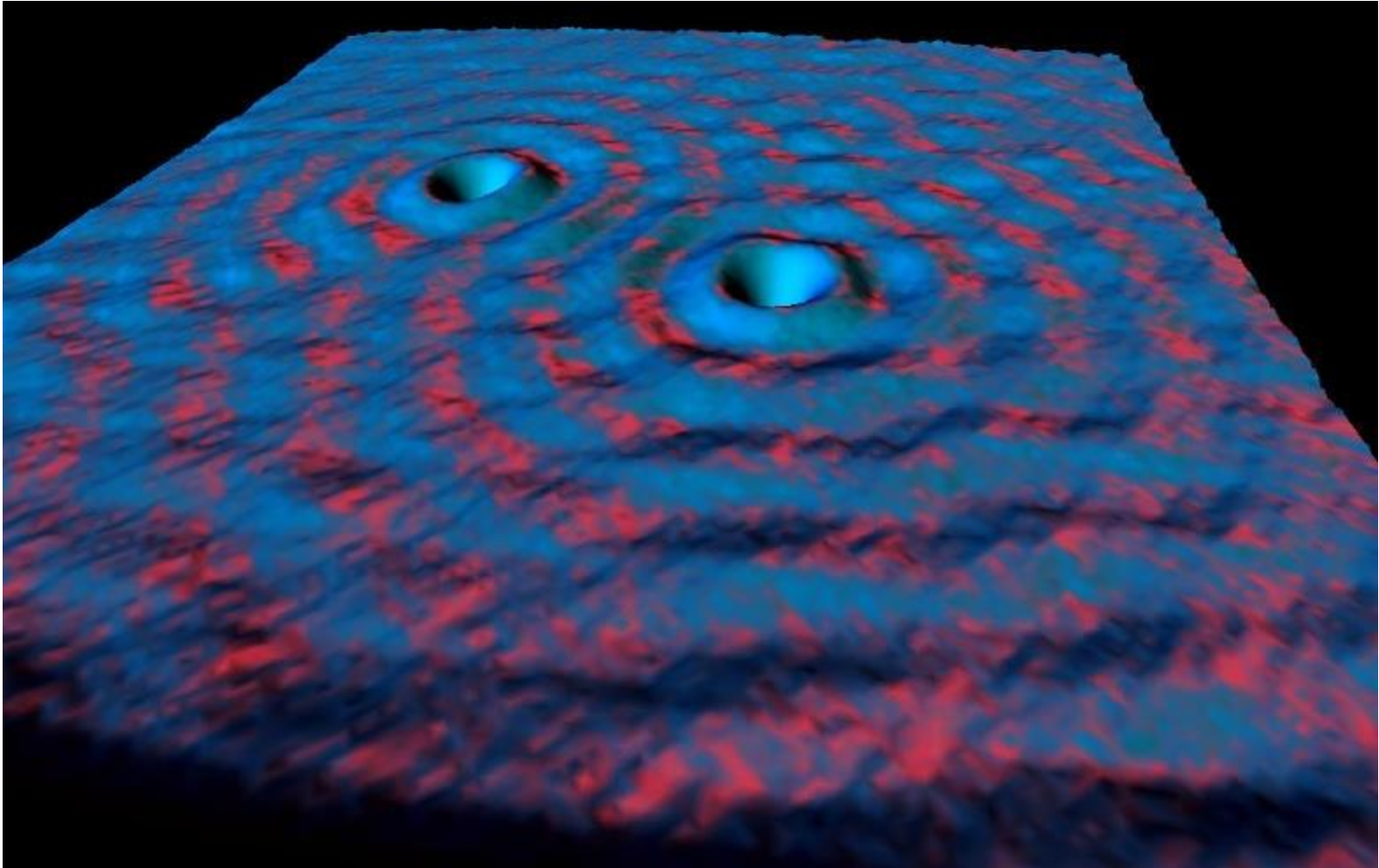
# NANOGRAPHICS



Iron atoms on the surface of Cu(111)

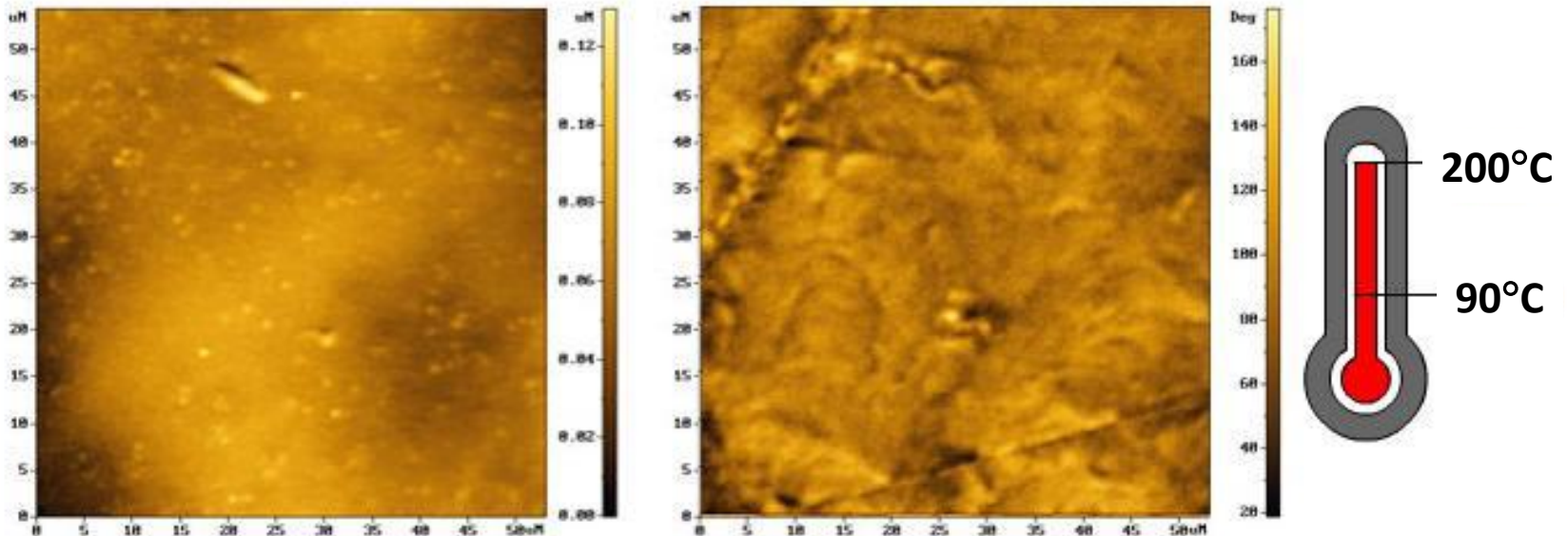


# NANOGRAPHICS



# MEASUREMENT AT VARIOUS TEMPERATURE

- requires application of dedicated heated stages and/or temperature chambers
- elements of the microscope must be resistant to elevated temperature
- investigation of the changes on oxide layers and alloys
- investigation of glass transition temperature of polymers
- observation of precipitation phenomena in solutions



*Images of polymer surface below and above glass transition temperature*

# ADVANTAGES OF ATOMIC FORCE MICROSCOPY

- ❖ modern technique providing insight into surface properties of the material in micro- and nanoscale, inaccessible via the conventional methods
- ❖ a result of measurement is an image of high resolution – in advantageous conditions even of atomic resolution
- ❖ wide range of the measurement modes providing universal character of the method
- ❖ measurement of not only topography but several other physical and electrical quantities (hardness, coefficient of friction, conductivity, magnetic properties)
- ❖ measurements can be carried out in controlled atmosphere (vacuum, inert gas, solution) and temperature
- ❖ possibility of monitoring changes of the surface versus time
- ❖ very useful tool for analysis of new materials, at the design or pre-implementation stages – verification of effectiveness of introduced modifications
- ❖ indispensable tool in developing field of nanotechnology (biotechnology, electronics, precision mechanics, failure analysis)

# DISADVANTAGES OF ATOMIC FORCE MICROSCOPY

- ❖ provides information only about surface properties of the material, not about bulk features
- ❖ high cost of equipment, execution of the measurement calls for qualified personnel
- ❖ sensitive to interference (vibrations, noise, air movement, electromagnetic noise)
- ❖ image interpretation can be troublesome – no information about chemical character of the investigated surface unless suitable adds-on are applied, for instance XPS
- ❖ necessity of application of the supplementary techniques to confirm the results obtained
- ❖ difficulties in landing the tip in exactly the sample place for the second time (need for precise sample markers)
- ❖ limited to laboratory applications